



Vision Based Road Traffic Violation Detection

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Abstract - In response to rising traffic challenges, we introduce an advanced approach using YOLOv8 Instance Segmentation and ByteTrack to efficiently detect pedestrian crossing violations. Achieving accuracies: Random Forest Classifier (98.08%), SVM (74.60%), and XGBoost model (99.20%), we have enhanced accuracy by training a 2D feature matrix with relevant pedestrian and vehicle features, ensuring safer pedestrian crossings.

Introduction

- Annual road fatalities in Sri Lanka exceed 2500.
- Building infrastructure and promoting discipline reduces traffic accidents.
- Bringing discipline by detecting traffic violations.
- Conventional methods of violation detection not being scalable with growing traffic.
- Need for an efficient, reliable, scalable, consistent violation detection method.

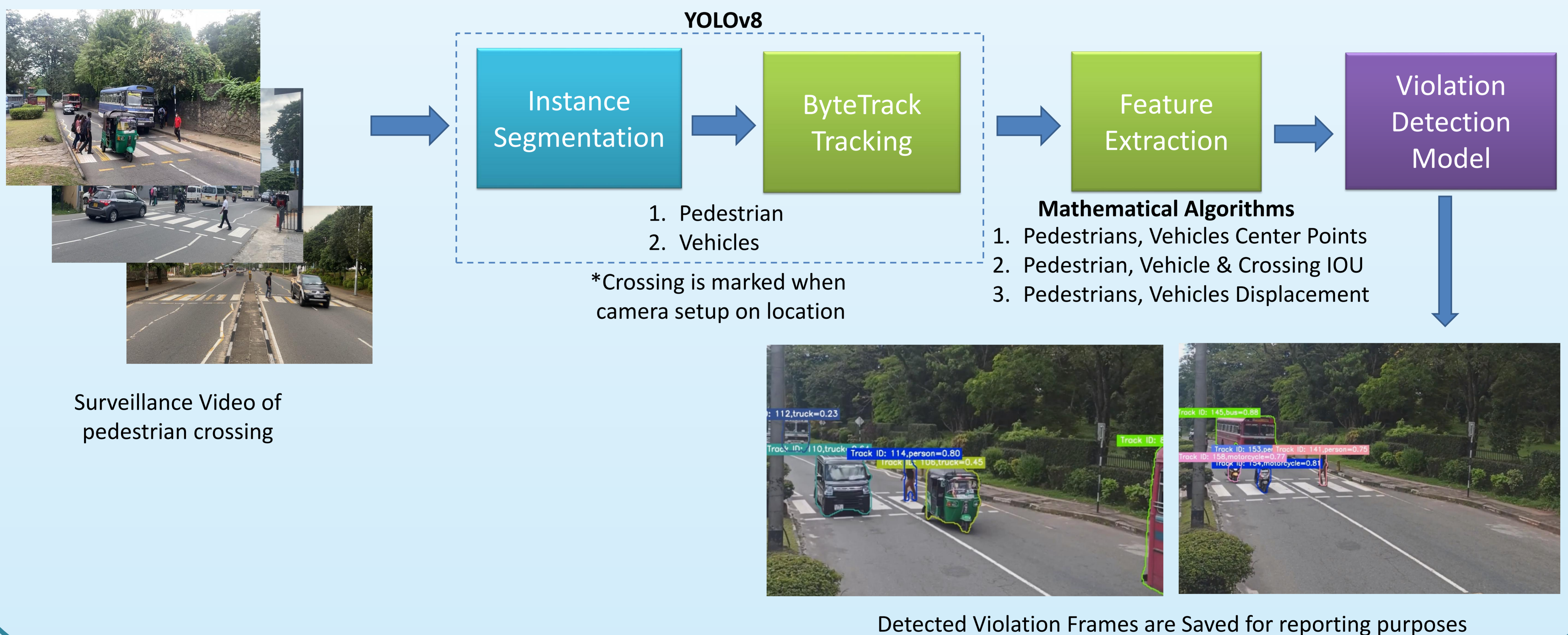
Approach

- YOLOv8 for vehicle and pedestrian Instance Segmentation
- ByteTrack algorithm for tracking
- Violation detection
 - **Random Forest**
 - **SVM**
 - **XGBoost**

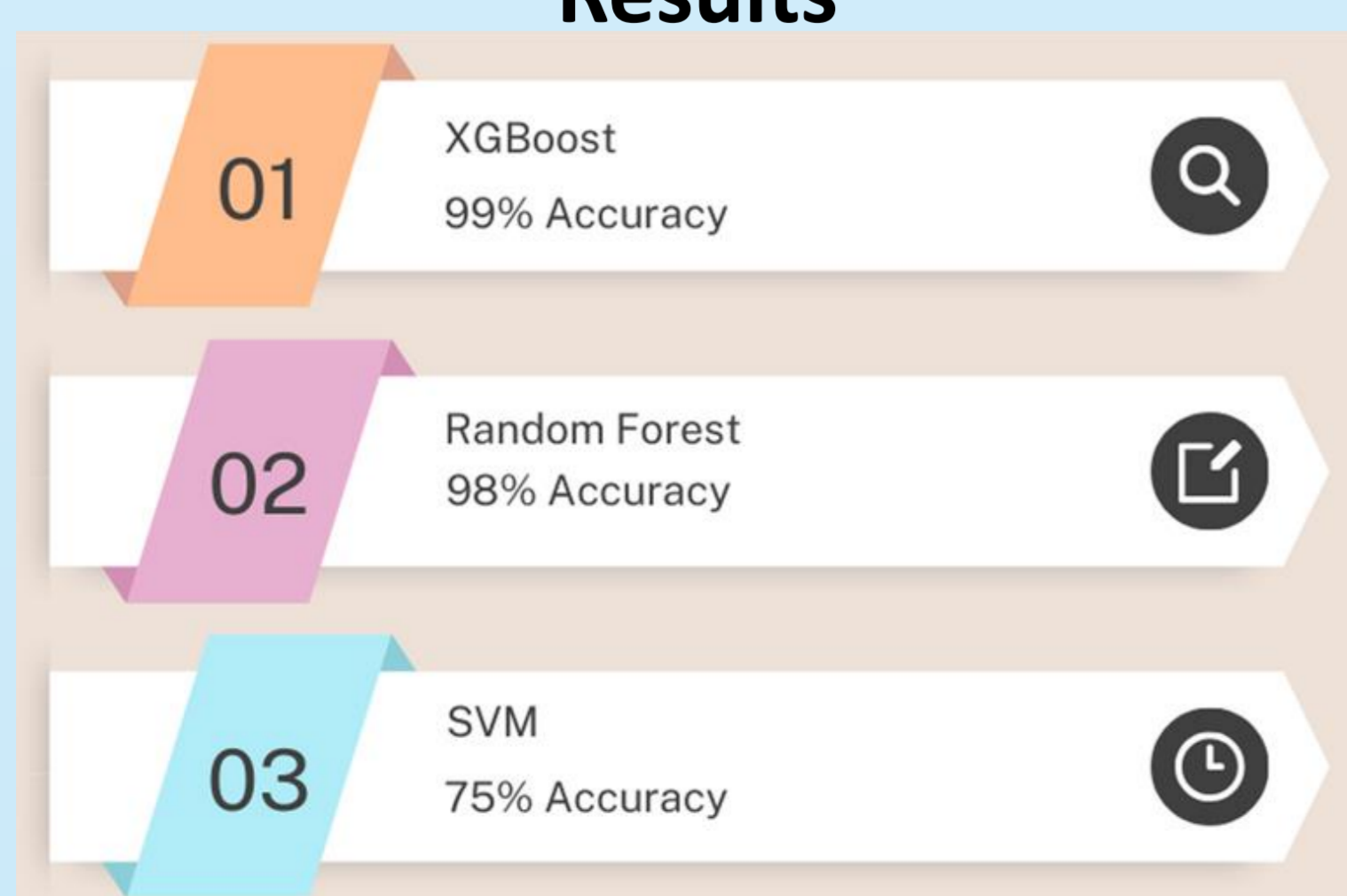
Feature Extraction

- Centers of Pedestrian and Vehicle
- Displacements of the Pedestrian and Vehicle between subsequent frames
- IOU of Pedestrian/Vehicle with Crossing
- Used the feature matrix as the key input for machine learning models.

Methodology



Results



Conclusion

- In Sri Lanka, we combat vehicle violations at pedestrian crossings using YOLOv8, ByteTrack, and ML model SVM, Random Forest, and XGBoost for precise detection.
- Improved accuracy is achieved through algorithms and feature matrix training
- Our approach combines feature extraction, object detection, object tracking, and machine-learning training models.
- By saving violation frames for reporting purposes, we aim to create a system that contributes to the reduction of traffic violations

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